

# THE APPLICATION OF THE INTERSECT INDEX TO QUASILINEAR EIGENFUNCTION PROBLEMS

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First time the intersect index was applied to non-linear problems in L. Lusternick's research. This direction is investigating at voronezh school now [1,2]. Small eigenfunctions and its global branches was considered by the intersect index in [3-5].

**1. Definitions.** We are interested in eigenvalues (e.v.)  $\lambda \in \mathbf{R}$  and eigenfunctions (e.f.)  $u \in W_2^1(\Omega)$  of the quasilinear problem

$$\Delta u + p(u, \text{grad}(u), x)u + \lambda u = 0, \quad u|_{\partial\Omega} = 0 \quad (1)$$

$$u \in S_R^\infty = \left\{ u : \int_{\Omega} u^2 = R^2 \right\} \quad (R > 0), \quad (2)$$

where  $W_2^k(\Omega)$  is Sobolev's space with norm  $\|\cdot\|_k$ ,  $\Omega \subset \mathbf{R}^n$  is a bounded domain with smooth boundary  $\partial\Omega$ ,  $x \in \bar{\Omega}$ ,  $\Delta$  is Laplas operator,  $p$  is a continue function. For simplicity of a priori estimates we have to suppose  $m < p(u, y, x) < M$   $((u, y, x) \in \mathbf{R}^{n+1} \times \bar{\Omega})$ .

The pair  $(\lambda, u)$  which satisfy (1),(2) is called *normalised solution* (n.s.). If  $(\lambda^*, u^*)$  is a n.s. then  $\lambda^*$  is an e.v. of the linear problem

$$\Delta u + q(x)u + \lambda u = 0, \quad u|_{\partial\Omega} = 0, \quad (3)$$

where

$$q(x) = p(u^*(x), \text{grad}(u^*(x)), x). \quad (4)$$

The e.f.  $u^*$  is among eigenfunctions of the problem (3),(4) certainly. The linear problem (3),(4) is symmetric that is why  $\lambda \in \mathbf{R}$ . Eigenvalues of (3) form the nondecreasing sequence  $\lambda_0 < \lambda_1 \leq \lambda_2 \leq \dots; \lambda_n \rightarrow \infty$ .

**D e f. 1.** The n.s.  $(\lambda^*, u^*)$  of the problem (1),(2) is named *the simple (n-multiple)*, if  $\lambda^*$  is simple ( $n$ -multiple) for the linear problem (3),(4). (The multiplicity of e.v. is finite always.)

**D e f. 2.** The n.s.  $(\lambda^*, u^*)$  of the problem (1),(2) and its elements have such number which the e.v.  $\lambda^*$  has as a eigenvalue of the linear problem (3),(4).

We need a priori estimates of normalised solutions which have bounded numbers.

**L e m m a 1.** *Eigenvalues  $\lambda$  with number  $n$  of the problem (1),(2) satisfy estimates  $\lambda_n - M < \lambda < \lambda_n + m$  where  $\lambda_n$  is the e.v. with number  $n$  of the problem (3) with  $q(x) \equiv 0$ .*

**L e m m a 2.** *Normalised solutions  $(\lambda, u)$  with number  $n$  of the problem (1),(2) satisfy the estimate  $|\lambda| + \|u\|_2 < C$  where the constant  $C$  depends on  $R, n, m, M$  only.*

The problem (1) is equal to the operator equation

$$u + (\lambda + M)A(u)u = 0, \quad (5)$$

due to lemma 1 where  $A$  is a continue mapping from  $W_2^1(\Omega)$  to Banach space  $L$  of linear symmetric compact operators.

We consider the family of linear equations

$$u + (\lambda + M)Bu = 0. \quad (6)$$

An operator  $B \in L$  is the parameter of the family. Let  $T_R^\infty = \{(B, u) \in L \times S_R^\infty : u \text{ is an e.f. of the problem (6)}\}$ . The set  $T_R^\infty$  is a smooth Banach manifold with model space  $L$  [6]. The manifold  $T_R^\infty$  is stratificated by numbers and multiplicity of its eigenfunctions:  $T_R^\infty(n, l) = \{(B, u) \in T_R^\infty : u \text{ is an e.f. of (6) with e.v. } \lambda, \text{ moreover } \lambda_{n-1}(B) < \lambda = \lambda_n(B) = \dots = \lambda_{n+l-1}(B) < \lambda_{n+l}(B)\}$ . Thus  $T_R^\infty = \bigcup_{n, l \in \mathbb{N}} T_R^\infty(n, l)$ . According to [7] it's possible to prove that  $T_R^\infty(n, l)$  is the smooth submanifold of  $T_R^\infty$  end  $\text{codim}T_R^\infty(n, l) = (l - 1)l/2$ . Notice  $\text{codim}T_R^\infty(n, 1) = 0$ ,  $\text{codim}T_R^\infty(n, 2) = 1$ . We give those number end multiplicity to a point  $(B, u) \in T_R^\infty$  which the e.f.  $u$  has.

We examine the mapping

$$Gr_A : S_R^\infty \longrightarrow L \times S_R^\infty, \quad Gr_A(u) = (A(u), u), \quad (7)$$

which is important for us.

**T h e o r e m 1.** *A function  $u$  is an e.f. of the equation (6) only in the case  $Gr_A(u) \in T_R^\infty$ . The number of solution  $(\lambda, u)$  and its multiplicity are defined by the index  $(n, l)$  of stratum  $T_R^\infty(n, l)$ :  $Gr_A(u) = (A(u), u) \in T_R^\infty(n, l) \subset T_R^\infty$ .*

**D e f. 3.** A mapping  $A$  is called *n-typical* if the image of the mapping (7) doesn't intersect stratums  $T_R^\infty(n, l)$  where the multiplicity  $l \geq 2$ . Other words solutions with number  $n$  are simple.

We will show that simple solutions can be obtained by the intersect index.

**2. Intersect index.** At first we consider the finite dimensional problem

$$v + \gamma K(v)v = 0, \quad v \in S^{k-1}, \quad (8)$$

which is analogous to the problem (5);  $K$  is a continue mapping from  $S^{k-1}$  to the space  $L^k$  of real symmetric  $k$ -dimensional matrixes. Definitions 1-3 have the sense in the problem (8). Manifolds  $T^k$ ,  $T^k(n, l)$ , the mapping  $Gr_K$  are determined by analogy with  $T_R^\infty$ ,  $T_R^\infty(n, l)$ ,  $Gr_A$  accordingly. Theorem 1 is true in case of the problem (8).

**L e m m a 3.** *The set of n-typical mappings  $K$  is opened and dense in the space of continue mappings from  $S^{k-1}$  to  $L^k$ .*

Since  $\text{dim}T^k = \text{dim}L^k$  for any  $n \leq k$  and an  $n$ -typical mapping  $K$  is determined the orientated intersect index  $\chi(\bar{T}^k(n, 1), Gr_K) = \chi(n, K)$  ( $\bar{T}^k(n, 1)$  is the closure of the stratum  $T^k(n, 1)$ ). If the index isn't equal to zero then the equation (8) has a n.s. with number  $n$ . The calculation of the index is a difficult problem due to the manifold  $\bar{T}^k(n, 1)$  has the boundary.

Let  $\{u_0, u_1, \dots\}$  be the set of eigenfunctions of some operator  $B \in L$ . Let  $\mathbf{R}^k \subset W_2^1(\Omega)$  ( $k = 1, 2, \dots$ ) be the finite dimensional subspace which is generated by the basis

$\{u_0, u_1, \dots, u_{k-1}\}$ . Let  $P^k$  be the orthogonal projection on  $\mathbf{R}^k$ . We replace the problem (5),(2) by the approximate equation

$$v + (\lambda + M)P^k A(v)v = 0, \quad v \in S^{k-1}, \quad (9)$$

which has type of (8). If a mapping  $A$  is  $n$ -typical than the mapping  $P^k A$  is  $n$ -typical for any big  $k$  too. Therefore the index  $\chi(n, P^k A)$  is determined for any big  $k$ .

**T h e o r e m 2.** *Index  $\chi(n, P^k A)$  has not change for any big  $k$ .*

**D e f. 4.** Let  $L$  be a  $n$ -typical mapping. We determine that the orientated intersect index  $\chi(\overline{T}_R^\infty(n, 1), Gr_A) = \chi(n, P^k A)$ , where  $k$  is big enough.

If the index isn't equal to zero then the problem (5),(2) has a n.s. with number  $n$ . Moreover, the solution is the limit ( $k \rightarrow \infty$ ) of solutions of equations (9) due to a priori estimates (lemma 2).

The intersect index is an invariant of a homotopy in the class of  $n$ -typical mappings. In our opinion a control of  $n$ -typeness isn't easy. For small eigenfunctions  $n$ -typeness are checked in a finite dimensional kernel of the linear problem

$$\Delta u + p(0, 0, x)u + \lambda^* u = 0, \quad u|_{\partial\Omega} = 0, \quad (10)$$

where  $\lambda^*$  is the e.v. of the problem (10) [3,4].

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